

CLAIMS

What is claimed is:

1        1. A method comprising:  
2            reading at least one sequence of images;  
3            preparing autocrop data for each image of each of the sequences of images; and  
4            storing autocrop data for each key frame of the sequences of images.

1        2. The method of Claim 1 wherein preparing autocrop data comprises:  
2            determining the active region of a current image of the sequences of images.

1        3. The method of Claim 2 wherein determining the active region comprises:  
2            selecting a portion of the current image as the active region of the current image  
3            such that all pixels outside the active region have no opacity.

1        4. The method of Claim 3 wherein selecting a portion comprises:  
2            reading the current image;  
3            locating a first vertical line of pixels with at least one pixel having non-zero opacity  
4            closest to the origin of the image;  
5            locating a second vertical line of pixels with at least one pixel having non-zero  
6            opacity furthest from the origin of the image;  
7            locating a first horizontal line of pixels with at least one pixel having non-zero  
8            opacity closest to the origin of the image;  
9            locating a second horizontal line of pixels with at least one pixel having non-zero  
10          opacity furthest from the origin of the image; and  
11          storing data specifying the active region of the current image.

1        5. The method of Claim 4 wherein  
2            locating the first vertical line and locating the second vertical line are performed  
3            before locating the first horizontal line and locating the second horizontal line; and  
4            locating the first horizontal line and locating the second horizontal line each  
5            comprise examining pixels between the first vertical line and the second vertical line.

1        6. The method of Claim 4 wherein  
2            locating the first horizontal line and locating the second horizontal line are  
3            performed before locating the first vertical line and locating the second vertical line; and  
4            locating the first vertical line and locating the second vertical line each comprise  
5            examining pixels between the first horizontal line and the second horizontal line.

1           7. The method of Claim 4 wherein storing data specifying the active region of  
2 the current image comprises:

3           storing the x coordinate of the first vertical line, the x coordinate of the second  
4 vertical line, the y coordinate of the first horizontal line, and the y coordinate of the second  
5 horizontal line.

*SUB A1*  
1           8. The method of Claim 1 further comprising:  
2 determining which images of each of the sequences of images are key frames.

1           9. The method of Claim 8 wherein determining comprises:  
2 determining whether the current image is the first frame of one of the sequences of  
3 images, and, if so, designating the current image as a key frame;  
4 determining whether the active region of the current image is outside the active  
5 region of a prior image, and, if so, designating the current image as a key frame; and  
6 determining whether smoothing is needed, and, if so, designating the current image  
7 as a key frame.

1           10. The method of Claim 9 wherein determining whether smoothing is needed  
2 comprises:  
3 calculating the difference in area between the active region of the current image and  
4 the active region of the prior image; and  
5 comparing the difference in area with a smoothing factor.

1           11. The method of Claim 10 wherein the smoothing factor is a numerical value  
2 set by a user.

1           12. The method of Claim 9 wherein the active region is a portion of any image  
2 such that all pixels outside the active region of the image have no opacity.

1           13. The method of Claim 2 further comprising:  
2 adding a boundary to the active region of the current image.

1           14. The method of Claim 13 wherein the boundary is a numerical value set by a  
2 user.

1        15. A machine readable medium having stored thereon instructions which when  
2 executed by a processor cause the machine to perform operations comprising:  
3            reading at least one sequence of images;  
4            preparing autocrop data for each image of each of the sequences of images; and  
5            storing autocrop data for each key frame of the sequences of images.

1        16. The machine readable medium of Claim 15 wherein preparing autocrop data  
2 causes the machine to perform operations comprising:  
3            determining the active region of a current image of the sequences of images.

1        17. The machine readable medium of Claim 16 wherein determining the active  
2 region data causes the machine to perform operations comprising:  
3            selecting a portion of the current image as the active region of the current image  
4 such that all pixels outside the active region have no opacity.

1        18. The machine readable medium of Claim 17 wherein selecting a portion  
2 causes the machine to perform operations comprising:  
3            reading the current image;  
4            locating a first vertical line of pixels with at least one pixel having non-zero opacity  
5 closest to the origin of the image;  
6            locating a second vertical line of pixels with at least one pixel having non-zero  
7 opacity furthest from the origin of the image;  
8            locating a first horizontal line of pixels with at least one pixel having non-zero  
9 opacity closest to the origin of the image;  
10          locating a second horizontal line of pixels with at least one pixel having non-zero  
11 opacity furthest from the origin of the image; and  
12          storing data specifying the active region of the current image.

1        19. The machine readable medium of Claim 18 wherein:  
2            locating the first vertical line and locating the second vertical line are performed  
3 before locating the first horizontal line and locating the second horizontal line; and  
4            locating the first horizontal line and locating the second horizontal line each  
5 comprise examining pixels between the first vertical line and the second vertical line.

1           20. The machine readable medium of Claim 18 wherein:  
2           locating the first horizontal line and locating the second horizontal line are  
3           performed before locating the first vertical line and locating the second vertical line; and  
4           locating the first vertical line and locating the second vertical line each comprise  
5           examining pixels between the first horizontal line and the second horizontal line.

1           21. The machine readable medium of Claim 18 wherein storing data specifying  
2           the active region of the current image causes the machine to perform operations comprising:  
3           storing the x coordinate of the first vertical line, the x coordinate of the second  
4           vertical line, the y coordinate of the first horizontal line, and the y coordinate of the second  
5           horizontal line.

1           22. The machine readable medium of Claim 15 having stored thereon further  
2           instructions which when executed by the processor cause the machine to perform further  
3           operations comprising:  
4           determining which images of each of the sequences of images are key frames.

1           23. The machine readable medium of Claim 22 wherein determining causes the  
2           machine to perform operations comprising:  
3           determining whether the current image is the first frame of one of the sequences of  
4           images, and, if so, designating the current image as a key frame;  
5           determining whether the active region of the current image is outside the active  
6           region of a prior image, and, if so, designating the current image as a key frame; and  
7           determining whether smoothing is needed, and, if so, designating the current image  
8           as a key frame.

1           24. The machine readable medium of Claim 23 wherein determining whether  
2           smoothing is needed causes the machine to perform operations comprising:  
3           calculating the difference in area between the active region of the current image and  
4           the active region of the prior image; and  
5           comparing the difference in area with a smoothing factor.

1           25. The machine readable medium of Claim 24 wherein the smoothing factor is  
2           a numerical value set by a user.

1           26. The machine readable medium of Claim 23 wherein the active region is a  
2           portion of any image such that all pixels outside the active region of the image have no  
3           opacity.

1           27. The machine readable medium of Claim 16 having stored thereon further  
2 instructions which when executed by the processor cause the machine to perform further  
3 operations comprising:  
4           adding a boundary to the active region of the current image.

*substantially similar to the claims above*

1           28. The machine readable medium of Claim 13 wherein the boundary is a  
numerical value set by a user.

1           29. A system comprising:  
2           a processor coupled to a bus;  
3           a memory coupled to the bus;  
4           a storage device coupled to the bus, the storage device having stored thereon  
5 instructions which when executed by the processor cause the system to perform operations  
6 comprising:  
7           reading at least one sequence of images;  
8           preparing autocrop data for each image of each of the sequences of images;  
9           and  
10           storing autocrop data for each key frame of the sequences of images  
11           on the storage device.

1           30. The system of Claim 29 wherein preparing autocrop data causes the system  
2 to perform operations comprising:  
3           determining the active region of a current image of the sequences of images.

1           31. The system of Claim 30 wherein determining the active region data causes  
2 the system to perform operations comprising:  
3           selecting a portion of the current image as the active region of the current image  
4 such that all pixels outside the active region have no opacity.

1           32. The system of Claim 31 wherein selecting a portion causes the system to  
2 perform operations comprising:  
3           reading the current image;  
4           locating a first vertical line of pixels with at least one pixel having non-zero opacity  
5 closest to the origin of the image;  
6           locating a second vertical line of pixels with at least one pixel having non-zero  
7 opacity furthest from the origin of the image;  
8           locating a first horizontal line of pixels with at least one pixel having non-zero  
9 opacity closest to the origin of the image;

10           locating a second horizontal line of pixels with at least one pixel having non-zero  
11    opacity furthest from the origin of the image; and  
12    storing data specifying the active region of the current image.

1           33.    The system of Claim 32 wherein:  
2           locating the first vertical line and locating the second vertical line are performed  
3    before locating the first horizontal line and locating the second horizontal line; and  
4           locating the first horizontal line and locating the second horizontal line each  
5    comprise examining pixels between the first vertical line and the second vertical line.

1           34.    The system of Claim 32 wherein:  
2           locating the first horizontal line and locating the second horizontal line are  
3    performed before locating the first vertical line and locating the second vertical line; and  
4           locating the first vertical line and locating the second vertical line each comprise  
5    examining pixels between the first horizontal line and the second horizontal line.

1           35.    The system of Claim 32 wherein storing data specifying the active region of  
2    the current image causes the system to perform operations comprising:  
3           storing the x coordinate of the first vertical line, the x coordinate of the second  
4    vertical line, the y coordinate of the first horizontal line, and the y coordinate of the second  
5    horizontal line.

1           36.    The system of Claim 29 having further instructions which when executed by  
2    the processor cause the system to perform further operations comprising:  
3           determining which images of each of the sequences of images are key frames.

1           37.    The system of Claim 36 wherein determining causes the system to perform  
2    operations comprising:  
3           determining whether the current image is the first frame of one of the sequences of  
4    images, and, if so, designating the current image as a key frame;  
5           determining whether the active region of the current image is outside the active  
6    region of a prior image, and, if so, designating the current image as a key frame; and  
7           determining whether smoothing is needed, and, if so, designating the current image  
8    as a key frame.

1           38.    The system of Claim 37 wherein determining whether smoothing is needed  
2    causes the system to perform operations comprising:

3 calculating the difference in area between the active region of the current image and  
4 the active region of the prior image; and  
5 comparing the difference in area with a smoothing factor.

*sub BATT*  
1 39. The system of Claim 37 wherein the active region is a portion of any image  
2 such that all pixels outside the active region of the image have no opacity.

1 40. The system of Claim 39 having stored thereon further instructions which  
2 when executed by the processor cause the system to perform further operations comprising:  
3 adding a boundary to the active region of the current image.

1 41. The system of Claim 29 wherein reading at least one sequence of images  
2 comprises:  
3 transferring at least one sequence of images from the storage device to the memory.

1 42. The system of Claim 29 wherein reading at least one sequence of images  
2 comprises:  
3 transferring at least one sequence of images from a remote storage device via a  
4 network.